

## Solutions to Exercise 4

**Problem 1.** Given that the *splitter* will be called concurrently by a number of  $N$  threads, we can think about this as selecting 1 thread to return *stop*. All the threads arriving during this election but not chosen to return *stop* can return *left*, and the ones arriving after the election can return *right*. It is acceptable to not have any threads selected to get *stop* (e.g., in case more than 1 thread executes *splitter*), but it must never be possible to have more than 1 thread return *stop* during a concurrent execution.

We use two registers:

- $P$  (multi-valued), and
- $S$  (binary, initialized to *false*)

$P$  holds the *id* of the thread that should get *stop*.  $S$  marks whether a *stop* thread has been selected. When a thread calls *splitter*, it needs to check whether  $S$  is *false*, and if so, set it to *true* and return *stop*. The difficulty is that we cannot use atomic *getAndSet*-type primitives, so multiple threads first reading the value of  $S$  and then updating it could mistakenly think they each got *stop*. In order to decide which thread should get *stop*, each thread volunteers itself by setting the value of  $P$  to their own id. The last thread to update  $P$  wins.

After volunteering, a thread checks the  $S$  flag, and if it is *true*, then the thread knows it arrived after the election, and so it gets *right*. If  $S$  still *false*, then the thread (one of potentially many) arrived during the election, so it sets  $S$  to *true*, and checks if it won (i.e., if the value of  $P$  is equal to its own id). If the thread won, it simply gets *stop*. Otherwise, it means some other thread managed to change  $P$  after it, hence the current thread lost and gets *left*.

It is possible that a thread updates  $P$  and becomes the winner just as another thread sets  $S$  to *true*, but before checking to see if it won. In this case, 0 threads get *stop*, as the winner then reads  $S$ , finds it *true*, concludes it arrived after the election, and gets *right*.

However, it is impossible for more than 1 thread to get *stop*. Assume by way of contradiction that 2 threads with identifiers  $i$  and  $j$  both return *stop*. Furthermore, assume without loss of generality that thread  $i$  first performed the read of  $P$  and then thread  $j$  read  $P$ . Therefore, the order of events will be  $read_i(P = i) \rightarrow read_j(P = j)$  (i.e., since both threads return *stop* they read their own identifier when reading from  $P$ ). We furthermore know that both threads write register  $P$  at the beginning of their execution and since both threads return *stop* they read  $S$  to be *false*. So we have the following ordering of events:

- $write_i(P \leftarrow i) \rightarrow read_i(S = false) \rightarrow write_i(S \leftarrow true) \rightarrow read_i(P = i)$ .
- $write_j(P \leftarrow j) \rightarrow read_j(S = false) \rightarrow write_j(S \leftarrow true) \rightarrow read_j(P = j)$ .

Since thread  $i$  read  $P = i$  (and thread  $j$  read  $P = j$ ) it means that  $write_j(P \leftarrow j)$  takes place after  $read_i(P = i)$ . So we have:

- $write_i(P \leftarrow i) \rightarrow read_i(S = false) \rightarrow write_i(S \leftarrow true) \rightarrow read_i(P = i) \rightarrow write_j(P = j) \rightarrow read_j(S = false)$ .

This is a contradiction, since thread  $i$  wrote *true* to  $S$  and then  $j$  read *false* from  $S$ .

```
upon splitteri
   $P \leftarrow i$ ;
  if  $S$  then return "right";
   $S \leftarrow true$ ;
  if  $P = i$  then return "stop";
  return "left";
```

**Algorithm 1:** Sample implementation of the *splitter* object.

## Problem 2.

Algorithm 2 presents the pseudocode of an atomic wait-free snapshot as described in class. For a program running  $N$  threads, in order to run a *scan* or a *collect* operation, all the registers of the  $N$  threads need to be read. Writes are done only on a thread's register  $R[i]$ . Since we know beforehand that many of the  $N$  threads will not use the snapshot, a better solution is to assign registers to threads on demand.

We assume that there exists an *obtain()* operation that each thread can call to get a register that is assigned only to itself. Algorithm 3 presents the implementation of *update()* and *scan()* using the aforementioned operation. Importantly, the number of registers that need to be parsed now in *scan()* is dependent on the number of threads that have written to the object (and thus have been assigned a register).

```
upon scani
  t1 ← collect(), t2 ← t1;
  while true do
    t3 ← collect();
    if t3 = t2 then return ⟨ t3[1].val, ..., t3[N].val ⟩ ;
    for k ← 1 to N do
      if t3[k].ts ≥ t1[k].ts + 2 then return t3[k].snapshot ;
    t2 ← t3;

procedure collect()
  for k ← 1 to N do
    x[k] ← R[k];
  return x;

procedure updatei(v)
  ts ← ts + 1;
  snapshot ← scan();
  R[i] ← ⟨ ts, v, snapshot ⟩;
```

**Algorithm 2:** Sample implementation of a non-adaptive snapshot. Each thread has its own register.

```
procedure update(v)
  if myreg = ⊥ then
    myreg ← obtain();
  ts ← ts + 1;
  snapshot ← scan();
  R[myreg] ← ⟨ ts, v, snapshot ⟩;

upon scani
  t1 ← collect(), t2 ← t1;
  while true do
    t3 ← collect();
    if t3 = t2 then return ⟨ t3[1].val, ..., t3[t3.length].val ⟩ ;
    for k ← 1 to t3.length do
      if t3[k].ts ≥ t1[k].ts + 2 then return t3[k].snapshot ;
    t2 ← t3;
```

**Algorithm 3:** Sample implementation of *update()* and *scan()* in an adaptive snapshot. Each thread that affects the snapshot calls *obtain()* to get assigned a register.

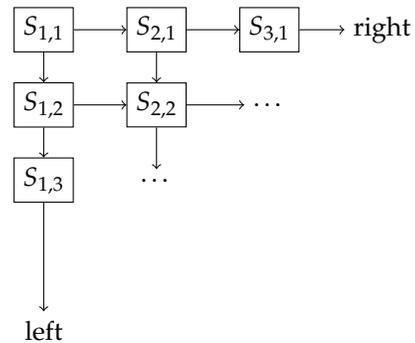
## Implementing *obtain()*

Recall the *splitter* object implemented in the previous exercise: it allows selecting at most 1 thread out of multiple accessing the object concurrently, while partitioning the remaining threads into 2 separate pools (*left*, *right*). Keeping this in mind, we create a matrix of *registers* and *splitters*, as presented in figure 1. A thread calling *obtain()* starts from the top-left corner and calls the *splitter* in that cell. If it gets *stop*, then it obtains that register. Otherwise, it moves 1 column to the *right*, or 1 row downwards for *left*, and repeats the process.

```

procedure obtain()
   $x \leftarrow 1, y \leftarrow 1;$ 
  while true do
     $s \leftarrow S[x, y].splitter();$ 
    if  $s = "stop"$  then return  $R[x, y];$ 
    else if  $s = "left"$  then  $y \leftarrow y + 1;$ 
    else  $x \leftarrow x + 1;$ 

```



**Algorithm 4:** Implementation of *obtain()* using a matrix of registers and *splitter* objects.

**Figure 1:** Matrix of registers and *splitter* objects.

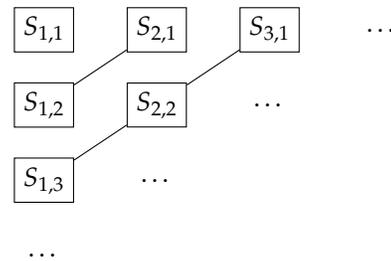
## Implementing *collect()*

Finally, we need to adapt the *collect()* call to the matrix of registers now being used. The insight here is that all the registers that have been assigned from each matrix diagonal that has had at least 1 splitter used need to be taken into account.

```

procedure collect()
   $C \leftarrow \langle \rangle;$ 
   $d \leftarrow 1;$ 
  while diagonal d has a splitter that has been
    traversed do
     $C \leftarrow C \cdot \langle \text{values of all non-}\perp \text{ registers}$ 
      on diagonal d  $\rangle;$ 
     $d \leftarrow d + 1;$ 
  return  $C;$ 

```



**Algorithm 5:** Implementation of *collect()* using a matrix of registers and *splitter* objects.

**Figure 2:** Matrix of registers and *splitter* objects.